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Malaria is one of the most important tropical diseases in the history of the world. This vector-borne disease has been a significant cause of morbidity and mortality in tropical countries of Africa, Asia, and Latin America. As such, this book provides updated information on epidemiological and public health research of malaria conducted in the last decade. Over four sections, chapters discuss such topics as diagnosis, epidemiology and surveillance, policy and prevention, and vector control and vaccines.

Technopoles - planned centres for the promotion for high- technology industry - have become a key feature of national economic development worldwide. Created out of a technological revolution, the formation of the global economy and the emergence of a new form of economic production and management, they constitute the mines and foundries of the information age, redefining the conditions and processes of local and regional development. This book is the first systematic survey of technopoles in all manifestations: science parks, science cities, national technopoles and technobel programmes. Detailed case studies, ranging from the Silicon Valley to Siberia and from the M4 Corridor to Taiwan, relate how global technopoles have developed, what each is striving to achieve and how well it is succeeding. Technopoles of the World distills the lessons learnt from the successes and failures, embracing a host of disparate concepts and a few myths, and offering guidelines for national, regional and local planners and developers worldwide.

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This book, Environmental Health Risk - Hazardous Factors to Living Species, is intended to provide a set of practical discussions and relevant tools for making risky decisions that require actions to reduce environmental health risk against environmental factors that may adversely impact human health or ecological balances. We aimed to compile information from diverse sources into a single volume to give some real examples extending concepts of those hazardous factors to living species that may stimulate new research ideas and trends in the relevant fields.

Soft computing, intelligent robotics and control are in the core interest of contemporary engineering. Essential characteristics of soft computing methods are the ability to handle vague information, to apply human-like reasoning, their learning capability and ease of application. Soft computing techniques are widely applied in the control of dynamic systems, including mobile robots. The present volume is a collection of 20 chapters written by respectable experts of the fields, addressing various theoretical and practical aspects in soft computing, intelligent robotics and control. The first part of the book concerns with issues of intelligent robotics, including robust xed point transformation design, experimental verification of the input-output feedback linearization of differentially driven mobile robot and applying kinematic synthesis to micro electro-mechanical systems design. The second part of the book is devoted to fundamental aspects of soft computing. This includes practical aspects of fuzzy rule interpolation, subjective weights based meta learning in multi criteria decision making, swarm-based heuristics for an area exploration and knowledge driven adaptive product representations. The last part addresses different problems, issues and methods of applied mathematics. This includes perturbation estimates for invariant subspaces of Hessenberg matrices, uncertainty and nonlinearity modelling by probabilistic metric spaces and comparison and visualization of the DNA of six primates.

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